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CORRELATION OF SEISMIC AMBIENT NOISE TO IMAGE AND TO MONITOR THE SOLID EARTH

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Definition

Seismic noise: permanent motion of the Earth surface that is not related to earthquakes or specific controlled sources.

Introduction

Traditional observational methods in seismology are based on earthquake records. It results in two main shortcomings. First, most techniques are based on waves emitted by earthquakes that occurred only in geologically active areas, mainly plate boundaries. This results in a limited resolution in all other areas where earthquakes are not present. Second, the repetition of earthquakes is rare, preventing the study of continuous changes within active structures such as volcanoes or faults.

Also at smaller scales in the context of geophysics prospecting, the resolution is limited by the number and power of sources, making it difficult to image large areas and/or deep structures. Similarly, reproducible sources are necessary for time-lapse monitoring leading to long-duration surveys that are difficult to achieve.

Nowadays, the seismic networks are producing continuous recordings of the ground motion. These huge amounts of data consist mostly of so called seismic noise, a permanent vibration of the Earth due to natural or industrial sources. Passive seismic tomography is based on the extraction of the coherent contribution to the seismic field from the cross-correlation of seismic noise between station pairs.

As described in many studies where noise has been used to obtain the Green's function between receivers, coherent waves are extracted from noise signals even if, at first sight, this coherent signal appears deeply buried in the local incoherent seismic noise. Recent studies on passive seismic processing have focused on two applications, the noise-extracted Green's functions associated to surface waves leads to subsurface imaging on scales ranging from thousands of kilometers to very short distances; on the other hand, even when the Green's function is not satisfactorily reconstructed from seismic ambient noise, it has been shown that seismic monitoring is feasible using the scattered waves of the noise-correlation function.

Theoretical basis for the interpretation of noise records at two stations

Passive seismology is an alternative way of probing the Earth's interior using noise records only. The main idea is to consider seismic noise as a wave field produced by randomly and homogeneously distributed sources when averaged over long time series. In this particular case, cross-correlation between two stations yields the Green's function between these two points. In the case of a uniform spatial distribution of noise sources, the cross-correlation of noise records converges to the complete Green's function of the medium, including all reflection, scattering, and propagation modes. However, in the case of the Earth, most of ambient seismic noise is generated by atmospheric and oceanic forcing at the surface. Therefore, the surface wave part of the Green's function is most easily extracted from the noise cross-correlations. Note that the surface waves are the largest contribution of the Earth response between two points at the surface.

Historically speaking, helioseismology was the first field where ambient-noise cross-correlation performed from recordings of the Sun's surface random motion was used to retrieve time-distance information on the solar

70 surface. More recently, a seminal paper was published by
 71 Weaver and Lobkis (2001) that showed how, at the labora-
 72 tory scale, diffuse thermal noise recorded and cross-
 73 correlated at two transducers fastened to one face of an
 74 aluminum sample provided the complete Green's function
 75 between these two points. This result was generalized to
 76 the case where randomization is not produced by the dis-
 77 tribution of sources, but is provided by multiple scattering
 78 that takes place in heterogeneous media.

79 By summing the contributions of all sources to the cor-
 80 relation, it has been shown numerically that the correlation
 81 contains the causal and acausal Green's function of the
 82 medium. Cases of non-reciprocal (e.g., in the presence of
 83 a flow) or inelastic media have also been theoretically
 84 investigated. Derode et al. (2003) proposed to interpret
 85 the Green's function reconstruction in terms of a time-
 86 reversal analogy that makes it clear that the convergence
 87 of the noise-correlation function towards the Green's
 88 function is bonded to the stationary phase theorem. For
 89 the more general problem of elastic waves, one could sum-
 90 marize that the Green's function reconstruction depends
 91 on the equipartition condition of the different components
 92 of the elastic field. In other words, the emergence of the
 93 Green's function is effective after a sufficient self-
 94 averaging process that is provided by random spatial dis-
 95 tribution of the noise sources when considering long-time
 96 series as well as scattering (e.g., Gouédard et al., 2008 and
 97 references herein).

98 Applications in seismology

99 For the first time, Shapiro and Campillo (2004)
 100 reconstructed the surface wave part of the Earth response
 101 by correlating seismic noise at stations separated by dis-
 102 tances of hundreds to thousands of kilometers, and mea-
 103 sured their dispersion curves at periods ranging from
 104 5 s to about 150 s. Then, a first application of passive seis-
 105 mic imaging in California (e.g., Shapiro et al., 2005; Sabra
 106 et al., 2005) appeared to provide a much greater spatial
 107 accuracy than for usual active techniques. More recently,
 108 the feasibility of using the noise cross-correlations to mon-
 109 itor continuous changes within volcanoes and active faults
 110 was demonstrated (e.g., Brenguier, 2008a, b). These
 111 results demonstrated a great potential of using seismic
 112 noise to study the Earth interior at different scales in space
 113 and time. At the same time, the feasibility of both noise-
 114 based seismic imaging and monitoring in every particular
 115 case depends on spatio-temporal properties of the avail-
 116 able noise wavefield. Therefore, a logical initial step for
 117 most of noise-based studies is to characterize the distribu-
 118 tion of noise sources. Also, in many cases, knowledge of
 119 the distribution of the noise sources can bring very impor-
 120 tant information about the coupling between the Solid
 121 Earth with the Ocean and the Atmosphere. So far, we
 122 can identify three main types of existing seismological
 123 applications related to noise correlations: (1) studies of
 124 spatio-temporal distribution of seismic noise sources,

(2) noise-based seismic imaging, and (3) noise-based seis- 125
 mic monitoring. 126

Noise source origin and distribution 127

128 Distribution of noise sources strongly depends on the 128
 129 spectral range under consideration. At high frequencies 129
 (> 1 Hz), the noise is strongly dominated by local sources 130
 that may have very different origins and are often anthro- 131
 pogenic. At these scales, the properties of the noise 132
 wavefield should be studied separately for every particular 133
 case and no reasonable generalization can be done. At lon- 134
 ger periods, noise is dominated by natural sources. In par- 135
 ticular, it is well established that two main peaks in the 136
 seismic noise spectra in so-called microseismic band 137
 (1–20 s) are related to forcing from oceanic gravity waves. 138
 It has been also argued that at periods longer than 20 s, the 139
 oceanic gravity and infragravity waves play a major role in 140
 the seismic noise excitation. The interaction between these 141
 oceanic waves and the solid Earth is governed by 142
 a complex non-linear mechanism (Longuet-Higgins, 143
 1950) and, as a result, the noise excitation depends on 144
 many factors such as the intensity of the oceanic waves 145
 but also the intensity of their interferences as well as the 146
 seafloor topography (e.g., Kedar et al., 2008). Overall, 147
 the generation of seismic noise is expected to be strongly 148
 modulated by strong oceanic storms and, therefore, to 149
 have a clear seasonal and non-random pattern. 150

151 Seismic noise in the microseismic spectral band is dom- 151
 152 inated by fundamental mode surface waves. It is currently 152
 debated whether the surface wave component of micro- 153
 154 seisms is generated primarily along coastlines or if it is 154
 also generated in deep-sea areas. Inhomogeneous distribu- 155
 156 tion and seasonality of microseismic noise sources is 156
 clearly revealed by the amplitude of the Rayleigh wave 157
 reconstructed in noise cross-correlations (e.g., Stehly 158
 et al., 2006) as shown in Figure 1. At the same time, body 159
 160 waves were detected in the secondary microseismic band 160
 and can be sometimes associated with specific storms. 161
 Figure 2 shows that sources of microseismic P waves are 162
 163 located in specific areas in deep ocean and exhibit strong 163
 164 seasonality as determined from the analysis of records 164
 by dense seismic networks (Landes et al., 2010). 165

Noise-based seismic imaging 166

167 Numerous studies has demonstrated that, when consid- 167
 168 ered over sufficiently long times, the noise sources 168
 169 become sufficiently well distributed over the Earth's sur- 169
 170 face and that dispersion curves of fundamental mode sur- 170
 171 face waves can be reliably measured from correlations of 171
 172 seismic noise at periods between 5 and 50 s for most of 172
 173 interstation directions. This led to the fast development 173
 174 during recent years of the ambient-noise surface wave 174
 175 tomography. It consists of computing cross-correlations 175
 176 between vertical and horizontal components for all avail- 176
 177 able station pairs followed by measuring group and phase 177
 178 velocity dispersion curves of Rayleigh and Love waves 178
 (e.g., Bensen et al., 2007). This dispersion curves are then 179

180 regionalized (e.g., Lin et al., 2009) and inverted to obtain
 181 three-dimensional distribution of shear velocities in the
 182 crust and the uppermost mantle. After first results obtained
 183 in southern California (Shapiro et al., 2005; Sabra et al.,
 184 2005), this method has been applied with many regional
 185 seismological networks (e.g., Yao et al., 2006; Lin et al.,
 186 2007; Yang et al., 2008a). At smaller scales, it can be used
 187 to study shallow parts of volcanic complexes (e.g.,
 188 Brenguier et al., 2007). The ambient-noise surface wave
 189 tomography is especially advantageous in context of
 190 dense continent-scale broadband seismic networks such
 191 as available in USA (e.g., Moschetti et al., 2007; Yang
 192 et al., 2008b) and Europe (e.g., Stehly et al., 2009). At
 193 these scales, noise-based imaging can be used to obtain
 194 high-resolution information about the crustal and the
 195 upper mantle structure including seismic anisotropy
 196 (e.g., Moschetti et al., 2010) and can be easily combined
 197 with earthquake-based measurements to extend the reso-
 198 lution to larger depths (e.g., Yang et al., 2008b). An exam-
 199 ple of results obtained from combined noise and
 200 earthquakes based surface wave tomography in western
 201 USA is shown in Figure 3.

202 Noise-based monitoring

203 One of the advantages of using continuous noise records
 204 to characterize the earth materials is that a measurement
 205 can easily be repeated. This led recently to the idea of
 206 a continuous monitoring of the crust based on the mea-
 207 surements of wave speed variations. The principle is to
 208 apply a differential measurement to correlation functions,
 209 considered as virtual seismograms. The technique devel-
 210 oped for repeated earthquakes (doublets), proposed by
 211 Poupinet et al., 1984, can be used with correlation func-
 212 tions. In a seismogram, or a correlation function, the delay
 213 accumulates linearly with the lapse time when the medium
 214 undergoes a homogeneous wave speed change, and
 215 a slight change can be detected more easily when consid-
 216 ering late arrivals. It was therefore reasonable, and often
 217 necessary, to use coda waves for the measurements of tem-
 218 poral changes. Noise-based monitoring relies on the auto-
 219 correlation or cross-correlation of seismic noise records
 220 (Sens-Schönfelder and Wegler, 2006; Brenguier et al.,
 221 2008a, b). When data from a network are available, using
 222 cross-correlation take advantage of the number of pairs
 223 with respect to the number of stations. It is worth noting
 224 that the use of the coda of the correlation functions is also
 225 justified by the fact that its sensitivity to changes in the ori-
 226 gin of the seismic noise is much smaller than the sensitiv-
 227 ity of the direct waves. Several authors noted that an
 228 anisotropic distribution of sources leads to small errors
 229 in the arrival time of the direct waves, which can be eval-
 230 uated quantitatively (e.g., Weaver et al., 2009). While in
 231 most of the cases, they are acceptable for imaging, they
 232 can be larger than the level of precision required when
 233 investigating temporal changes. The issue of the nature
 234 of the tail (coda) of the cross-correlation function is there-
 235 fore fundamental and was analyzed by Stehly et al. (2008).

These authors showed that it contains at least partially the
 236 coda of the Green function, i.e., physical arrivals which
 237 kinematics is controlled by the wave speeds of the
 238 medium. It can therefore be used for monitoring temporal
 239 changes. As an illustration of the capability of this
 240 approach, we present in Figure 4 a measure of the average
 241 wave speed change during a period of 6 years in the region
 242 of Parkfield, California. Two main events occurred in this
 243 region during the period of study: the 2003 San Simeon
 244 and 2004 Parkfield earthquakes. In both cases, noise-
 245 based monitoring indicates a co-seismic speed drop.
 246 The measured relative variations of velocity before de
 247 San Simeon earthquake are as small as 10^{-4} . The changes
 248 of velocity associated with earthquakes are associated
 249 with at least two different physical mechanisms: (1) the
 250 damage induced by the strong ground motions in shallow
 251 layers and fault zone, as illustrated by the co-seismic effect
 252 of the distant San Simeon event, and (2) co-seismic bulk
 253 stress change followed by the post-seismic relaxation, as
 254 shown with the long-term evolution after the local
 255 Parkfield event, similar in shape to the deformation mea-
 256 sured with GPS.
 257

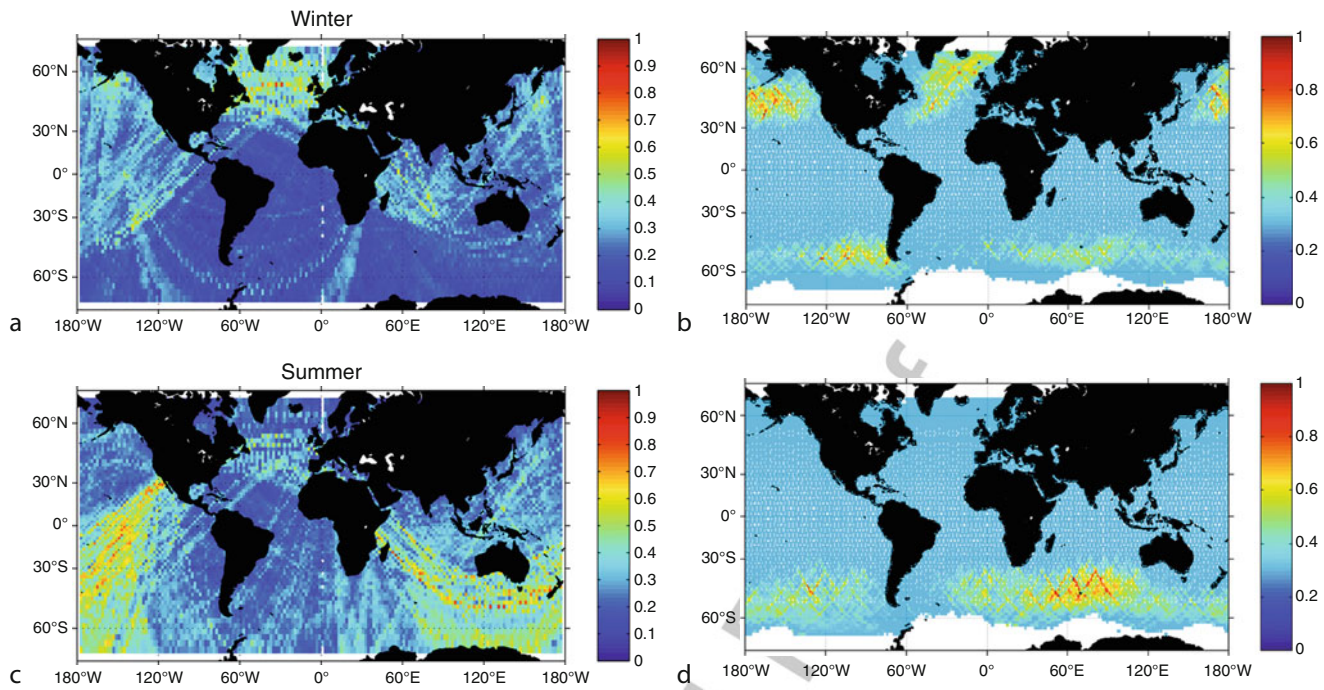
258 Summary

259 Continuous recordings of the Earth surface motion by
 260 modern seismological networks contain a wealth of infor-
 261 mation on the structure of the planet and on its temporal
 262 evolution. Recent developments shown here make it possi-
 263 ble to image the lithosphere with noise only and to detect
 264 temporal changes related to inner deformations.

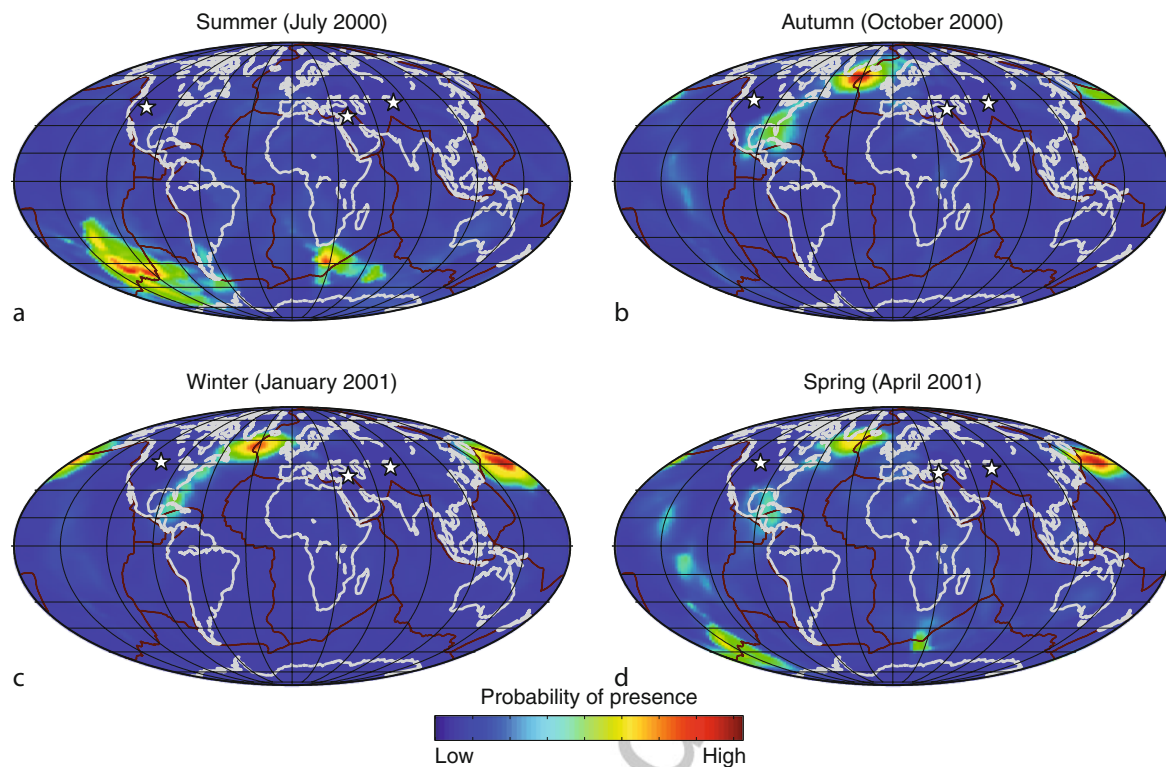
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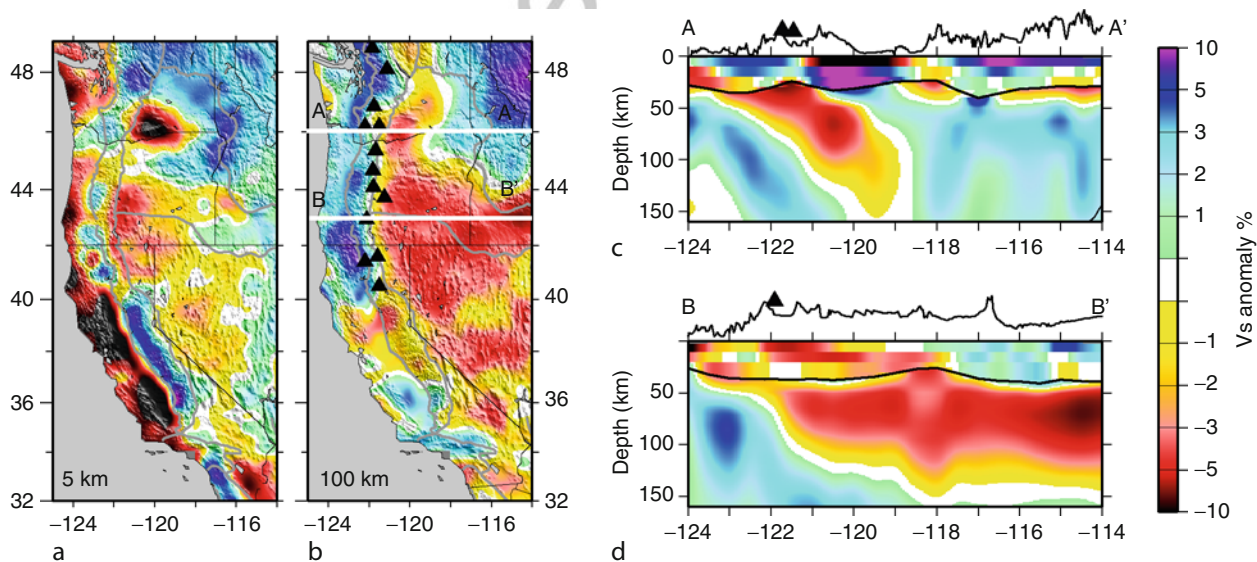
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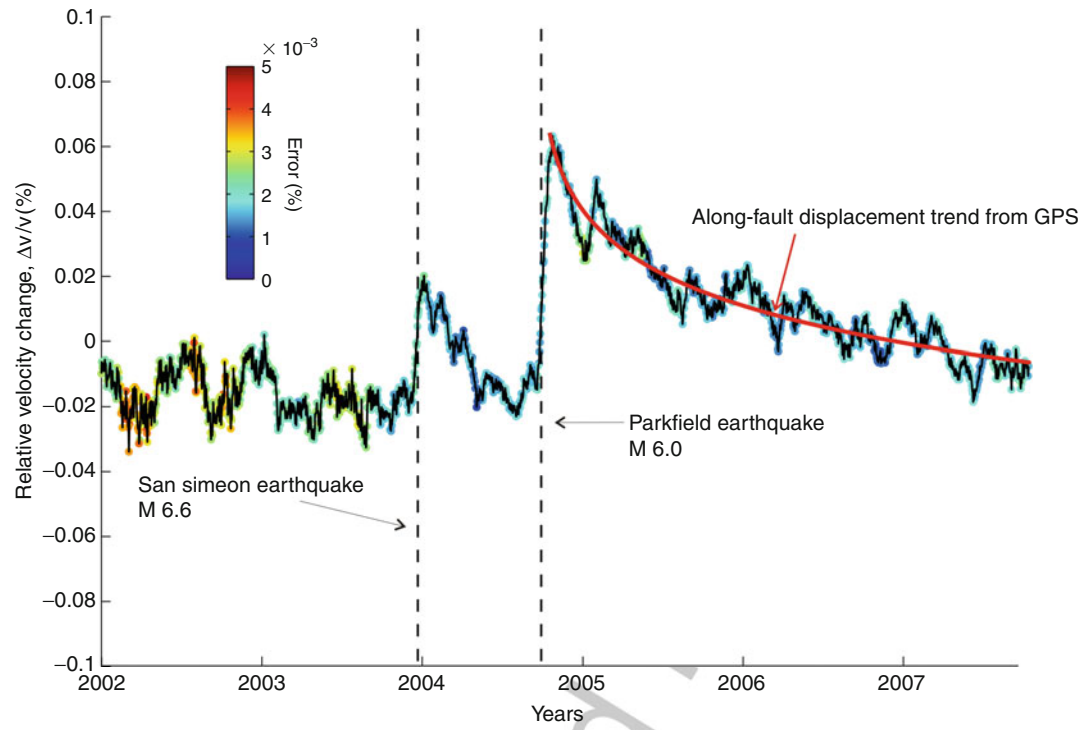
Correlation of Seismic Ambient Noise to Image and to Monitor the Solid Earth, Figure 1 Comparison between seasonal variations of the location of seismic noise sources and significant wave height. (a) and (c) Geographical distribution of the apparent source of the Rayleigh waves detected in the 10–20 s noise cross correlations during the winter and the summer, respectively. (b) and (d) Global distribution of the square of wave height measured by TOPEX/Poseidon during the winter and the summer, respectively (From Stehly et al., 2006).



Correlation of Seismic Ambient Noise to Image and to Monitor the Solid Earth, Figure 2 Seasonal variation of the location of P-wave seismic noise sources in the secondary microseismic band (0.1–0.3 Hz) determined from the analysis of records at the three seismic networks indicated with white stars (From Landes et al., 2010).



Correlation of Seismic Ambient Noise to Image and to Monitor the Solid Earth, Figure 3 Shear-velocity structure of the crust and the upper mantle obtained from the inversion of the USArray data. (a) and (b) Horizontal cross-sections at depths of 5 and 100 km. (c) and (d) Vertical cross-sections along profiles delineated by the white lines in (b). Black lines outline the Moho. Topography is superimposed above individual cross sections. The black triangles represent active volcanoes in the Cascade Range (From Yang et al., 2008b).



Correlation of Seismic Ambient Noise to Image and to Monitor the Solid Earth, Figure 4 Relative seismic velocity change during 6 years measured from continuous noise correlations in Parkfield. The dashed lines indicated two major earthquakes: the San Simeon event that occurred 80 km from Parkfield and the local Parkfield event (Modified from Brenguier et al., 2008b).